Digital Temperature Controller FY400/600/700/800/900 FU400/FU48/72/86/96

# **Operation Manual**



Ver 1.0



台灣儀控股份有限公司 TAIWAN INSTRUMENT & CONTROL CO., LTD

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### 1. Notice



- 1. Beware of Electric Shock!
- 2. Once controller is activated, do not touch AC power wiring terminals to avoid electric shock!
- 3. First to confirm power is OFF, before working on the wiring of controller power supply!
- 4. Before using this product, please read through this operating manual thoroughly to understand the correct usage based on the fundamentals of its conten.
- 5. This product can be used in industrial equipment, working terminal, measurement equipment, but not in life-savingrelated medical equipment.
- 6. In order to ensure safety even if the temperature controller fails, please set up another alarm system or safety redundancy.



- 1. Before the controller transmits power, make sure that the position of the AC power assembly leg is correct. Otherwise, the controller may be seriously damaged after power transmission is initiated.
- 2. Before powering on, please confirm whether the power supply voltage is in accordance with the controller's specification (AC 85~265V or DC 24V.) Otherwise, the controller may be seriously damaged after power transmission is initiated.
- 3. Check if the wiring is connected to the terminal for the correct terminals (Input, Output.)
- 4. Please use crimp terminals suitable for M3 screws, as shown below:



- 5. Do not install the controller in places subject to high-frequency interference, corrosive gases, and high temperature and humidity (normal working environment: 0 ~ 50°C, 20 ~ 90% RH.)
- 6. To avoid noise interference, please keep the sensor wiring away from the power cord and the loading power cord.
- 7. When the thermocouple lead is extended, please use the compensation lead of the corresponding type to this thermocouple.
- 8. When the RTD lead wire is extended, please use those with lower resistance value. Please use the same wire between the three Wires.

### 2. Order Information



Boxed-in items are optional functions, which shall incur extra charges.

# 3. Specifications

Model		FY400/FU400/48	FY600	FY700/FU72	FY800/FU86	FY900/FU96		
Supply V	′oltage	AC 85 ~ 265V, DC 24V (Optional Functions)						
Power Fr	requency	50/60 Hz						
Power C	onsumption	Approximately 6VA						
Memory	•	Non-Volatile Memo	orv EEPROM					
		Cold junction comp	pensation diode exte	rnal				
		Accuracy : 0.1%	pensation diode inter	mal				
		Accuracy : 0.3%		na				
Sensor Ir	nput	Sample time : 50m	s					
※ Please	e refer to Input	Thermalcouple: (K	、J、R、S、B、E、	$N \smallsetminus T \searrow W \searrow PL \amalg \char{\begin{subarray}{c} N & N & PL \end{array}}$	L)			
Range	e Table	RTD: PT100						
		DC Linear Analog	Input: 0~20mA \ 4~2	20mA				
			0~1V ∖ 0~5V	` 0~10V ` 0~2V ` 1⁄	~5V ` 2~10V			
			0~25mV ∖ 0~	50mV \ 0~70mV				
		1a 10 SPST NO. 250		1c	1c	1c		
	OUT I Relay	1c SPDT-NO, 250	VAC, 5A (resistive l	oad), electrical life: {	50,000 operations			
Output		SPDT-NC,	250 VAC, 2A (resis	tive load), electrical	life: 20,000 operatio	ns		
	OUT2 Relay	SPST-NO, 250 VA	C, 5A (resistive load	I), electrical life: 100	,000 operations			
	SSR Driver	ON: 24 V OFF: 0V	max. load current: 2	0mA, with short circ	uit protection circuit			
	linear	4~20mA,0~20mA,	0~5V,0~10V, 1~5V,	2~10V				
Control N	lethod	ON-OFF or P \ PI	<ul> <li>PID control</li> </ul>					
		1a	1c	1a	1c	1c		
	Alarm 1	1a SPST-NO, 250 VAC, 5A (resistive load), electrical life: 100,000 operations						
A 1 a maa		SPDT-NC, 250 VAC, 2A (resistive load), electrical life: 20,000 operations						
Alarm	Alarm 2	SPST-NO, 250 VA	C, 5A (resistive load	l), electrical life: 100	,000 operations			
	Alarm 3		1a	1a	1a	1a		
	Aidini 5	SPST-NO, 250 VAC, 5A (resistive load), electrical life: 100,000 operations						
	Re-transmitted Signal	4~20mA \ 0~20mA \ 0~5V \ 0~10V \ 1~5V \ 2~10V						
TRS	Source of Re- transmission	SV ^ PV						
	Accuracy	0.1%						
	Resolution	14 bit						
Remot	Signal	4~20mA \ 0~20mA \ 0~5V \ 0~10V \ 1~5V \ 2~10V						
e SV	Resolution	18 bit						
	Signal	5V 1KO \ 5600						
Motor	Resolution	18 bit						
vaive	controlled by	PV2						
	Interface	RS-485 Half duple	x Communication	MAX. 31 units, MAX	K. distance 1200 met	ers		
	Protocol	Modbus RTU , TAI	E					
Comm	Parity bit	NONE, ODD, EVE	N					
on	Data bit	8 bit						
-	Stop bit	1 or 2 bit						
	Baud rate	2400,4800,9600,19200,38400,57600,115200 bps						
Operating Environment		0 ~ 50°C (in the case of no freezing or condensatioin) / 20% ~ 90% RH						
Storage Tempera	Environment ture	-25 ~ 65°C (in the	case of no freezing	or condensatioin)				
Dimensio	on (mm)	W48 x H48 x D95	W96 x H48 x D95	W72 x H72 x D95	W48 x H96 x D95	W96 x H96 x D95		
weight		Appox.120g	Appox.170g	Appox.150g	Appox.170g	Appox.230g		

### 4. Input Range Table

Types of input			Cada	Range		
l yr	bes of input		Code	°C	°F	
	K	K1	01	-50.0~600.0	-58.0~999.9	
	n	K2	02	-50~1200	-58~2192	
		J1	03	-50.0~400.0	-58.0~752.0	
	J	J2	04	-50~1200	-58~2192	
	R	R	05	-50~1760	-58~3200	
	S	S	06	-50~1760	-58~3200	
Thormologunlo	В	В	07	-50~1820	-58~3308	
mermalcouple	E	E	08	-50~900	-58~1652	
	N	N	09	-50~1300	-58~2372	
	т	T1	10	-199.9~400.0	-199.9~752.0	
	1	T2	11	-199~400	-326~752	
	W	W	12	-50~2320	-58~4208	
	PL	PL	13	-50~1200	-58~2192	
	L	L	14	-50~800	-58~1472	
		PT1	15	-199.9~850.0	-199.9~999.9	
RTD	PT100	PT2	16	-199~850	-326~1562	
		PT3	17	0~850	32~1562	
	AN1	0~25mV	18			
		0~50mV	19			
		0~20mA	20			
		0~1V	21			
	AINZ	0~2V	22	-1.999	~9.999	
Lineer		0~5V	23	-19.99	~99.99	
Linear		0~10V	24	-199.9	~999.9	
	AN3	0~70mV	25	-1999	~9999	
		4~20mA	26			
	A.N.4	10~50mV	27			
	AIN4	1~5V	28			
		2~10V	29			

### 5. Packing List & Label Information

### 5.1 Packing List Guide

FY400/600/700/800/900

- Temperature Controller...1 unit
   Mounting frame......2 units
   Brief manual.....1 pcs

#### 5.2.1 FY400/FU400/FU48



No.	Item	Description
(1)	Terminal arrangement	FY400 Terminal Wiring Diagram
(2)	Model number	FY400 model name
(3)	Serial number	18112740001
(4)	Input type	Controller Input Signal and Scope

#### 5.2.2 FY700/FU72



No.	Item	Description
(1)	Terminal arrangement	FY700 Terminal Wiring Diagram
(2)	Model number	FY700 model name
(3)	Serial number	18112770001
(4)	Input type	Controller Input Signal and Scope



No.	Item	Description		
(1) Terminal arrangement		FY900 Terminal Wiring Diagram		
(2)	Model number	FY900 model name		
(3)	Serial number	18112790001		
(4)	Input type	Controller Input Signal and Scope		



### 7. Installation

### 7.1 FY400/FU400/FU48 Dimensions



### 7.2 FY600 Dimensions



### 7.3 FY700/FU72 Dimensions





### 7.5 FY900/FU96 Dimensions



### 8. Terminal Arrangement

### A Caution

When implementing wiring for the controller power supply, please make sure that the power supply is turned off to avoid electric shock!

Do not touch the live parts, such as the terminals, while the power is on. Otherwise death or serious injury may be resulted from short circuit of the contact electrode.

8.1 FY400/FU400/FU48 Terminal Arrangement





#### 8.3 FY700/FU72 Terminal Arrangement



#### 8.4 FY800/FU86 Terminal Arrangement



8.5 FY900/FU96 Terminal Arrangement



### 9. Basic Function Setting

### 9.1 Input Type Setting

1.	PV 886 SV 886	Display after power-on.	2.	PV SV	108 1 82	Hold SET key + key 3 seconds, to enter LEVEL_3 upper display showing "INP1" with lower display showing current input type.
3.	PV	Press key the lower display flashes.	4.	PV SV	INP I PE`{	Press key and key and key to enter the intended input type.
5.	PV III SV PE	Press SET key to store new value of INP1.	Moo and Plea	dify input it needs ase refer	type needs to in to recalibration to chapter 15. "	terchange of jumper location, for linear input type change. Input type modification".

#### 9.2 SV Value Setting

1.	PV 25 sv 29	Display after power-on.	2.	₽V <i>8825</i> sv <i>0000</i> 0	When key is pressed, the lower display flashes.
3.	₽V <i>8825</i> sv <i>0350</i>	Press 🗼 key and V key to adjust set value.	4.	PV 8725 SV 8750	Press <b>SET</b> key to store new value of SV.

### 9.3 Auto Tuning Execution

1.	PV <b>8865</b> SV <b>8150</b> Display after power-on.	2. PV <b>RES</b> Press <b>ET</b> key until show "AT" •
3.	PV <b>ALE</b> SV When key is pressed, the lower display flashes.	4. PV <b>FIE</b> SV <b>FIE</b>
5.	PV <b>BBEB</b> SV <b>BBES</b> Press <b>SET</b> key to store new value of AT.	When auto tuning AT LED lamp lit and start to output, through a few circles to get new PID value with the precise control, if finished the AT LED will be lamp off.

### 9.4 PID Value Setting

1.	PV 8825 sv 8158	Display after power-on.	2.	PV <b>27</b> 7 SV <b>27</b> 1	Hold <b>SET</b> key 3 seconds, then entering into LEVEL_2 upper display showing "P1", with lower display show current P1 value.
3.	pv <b>F</b> sv <b>0030</b>	When < key is pressed, the lower display flashes.	4.	PV <b>999</b> sv <b>0500</b>	Press key and key and key to set the intended P1 value.
5.	PV <b>F</b> 7 SV <b>500</b>	Press <b>SET</b> key to store new value of P1.	By the valu	e same procedure, use th le(I1) and derivative value	ne same ways to set integral e(D1).

### 9.5 ON/OFF Control Setting

1.	PV 8825 SV 8150	Display after power-on.	2. PV PI Hold set key 3 second then entering into LEV as upper display show with lower display show current P1 value.	nds, /EL_2, /s "P1", wing
3.	PV <b>2013</b> 0 SV <b>0030</b>	When key is pressed, the lower display flashes, upper display.	4. PV Press key until SV Press N key until P1 = $0.0$	
5.	PV <b>7</b> 78 SV <b>00</b>	Press set key to store new value.	6. PV <b>H95</b> 7 Press ser key until SV <b>H95</b> 7 "HYS1" •	show
7.	PV <b>H95</b> 1 sv <b>H95</b> 1	When key is pressed, the lower display flashes.	8. PV <b>H95</b> Press key and key to set the intended value.	V I HYS1
9.	PV <i>H551</i> sv 880	Press key to store new value.	Heat mode formula: PV > (SV + HYS1) → OUT1 OFF PV ≤ (SV - HYS1) → OUT1 ON Cool mode formula: PV ≥ (SV + HYS1) → OUT1 ON PV < (SV - HYS1) → OUT1 OFF	

### 9.6 Alarm Mode Setting

1.	PV 8825 sv 8880	Display after power-on.	2.	PV <b>////</b> sv <b>////</b>	Hold set key + key 3 seconds, then entering into LEVEL_3 upper display showing "INP1" with lower display showing current input type.
3.	PV <b>ALC</b> SV	Press <b>SET</b> key until show "ALD1" ∘	4.	PV <b>ALA</b> sv <u>AAA</u>	When key is pressed, the lower display flashes
5.	₽V <b>8Ldi</b> sv 1.2	Press key and key to set the intended ALD1 value.	6.	PV <b>8281</b> sv 818	Press <b>BET</b> key to store new value of ALD1. ※ Please refer to ch12.1 Alarm mode.

### 9.7 Alarm Value Setting

1.	PV SV	8.825 8880	Display after power-on.	2.	PV <b>AL</b> A sv <b>ALA</b>	Press SET key until show "AL1" •
3.	PV SV	RL 1 0000;	When key is pressed, the lower display flashes.	4.	PV <b>HL</b> sv <b>DDŽD</b>	Press key and key and key to set the intended AL1 value.
5.	PV SV	8127 0020	Press SET key to store new v	alue d	of AL1.	

#### 9.8 Manual Mode Selection

1.	PV 8825 sv 8358	Display after power-on.	2.	PV <b>DUED</b> SV <b>BOD</b> Hold AM 2 seconds.
3.	PV <i>8825</i> sv <i>0000</i>	When < key is pressed, the lower display flashes.	4.	PV <b>SV Press</b> key and key to set the intended output% value.
5.	PV <b>0000</b> sv <b>500</b>	Press SET key to store new value.	In n contii In n con	manual mode OUTL=100.0,output=100.0 % inuously. manual mode OUTL=20.0,output=20.0 % ntinuously.

#### 10. Flow Chart of Parameter Setting

#### 10.1 Level Operation Mode

- 1. <u>LEVEL 1 enter to the LEVEL 2</u> Hold SET key for 3 seconds then entering into LEVEL 2
- 2. <u>LEVEL 1 enter to the LEVEL 3</u> Hold SET key + SHIFT key for 3 seconds then entering into LEVEL 3
- 3. <u>LEVEL 2 return to the LEVEL 1</u> Hold SET key for 3 seconds then return to LEVEL 1
- 4. <u>LEVEL 2 enter to the LEVEL 3</u> Hold SET key for 3 seconds then entering to LEVEL 3
- <u>LEVEL 2 enter to the LEVEL 4</u> On the LEVEL 2 then press SET key to find parameter "LCK modify LCK value from current value to 1111 after hold SET key + SHIFT key 3 seconds entering into LEVEL 4
- 6. <u>LEVEL 3 return to the LEVEL 1</u> Hold SET key + SHIFT key for 3 seconds then return to LEVEL 1
- 7. <u>LEVEL 3 return to the LEVEL 2</u> Hold SET key for 3 seconds then return to LEVEL 2
- 8. <u>LEVEL 4 return to the LEVEL 1</u> Hold SET key + SHIFT key for 3 seconds then return to LEVEL 1
- 9. <u>LEVEL 4 return to the LEVEL 2</u> Hold SET key for 3 seconds then return to LEVEL 2



: If no key is pressed within 60 seconds, it will automatically return to LEVEL 1 (user level) and display PV/SV.

#### 10.3 Data Lock Function

LCK provides a parameter protection function to prevent the first line operator from touching or modifying important parameters. Conversely, when the parameter cannot be modified, please make sure that the set value of LCK.

		LI	EVEL		
LCK	Level_1	Level_2	Level_3	Level_4	Descriptions
0000	O	O	O	X	All parameters of Level 1, 2 & 3 are able to be modified (Factory default setting)
1111	0	0	х	0	All parameters of Level 1, 2 & 4 are able to be modified
0100	0	0	х	Х	All parameters of Level 1, 2 are able to be modified
0110	0	0	Х	Х	Only parameters of Level 1 and LCK can be modified
0001	0	0	х	Х	Only SV, LCK can be modified
0101	0	0	х	Х	Only LCK can be modified
Other	0	0	0	х	Once jumping to other levels, LCK will be automatically restored to 0000

 $\mathbb{O}$ : able to enter X: unable to enter



%: If no key is pressed within 60 seconds, it will automatically return to LEVEL 1 (user level) and display PV/SV

<b>D</b> (	O wash at	Content	Ra	nge		Hide/
Parameter	Symbol	Content	MAX	MIN	Default	Display
PV		Process value	USPL	LSPL		
SV		Set value	USPL	LSPL		
OUTL	BBEE	High limit setting of manipulated value main output when PID gain > OUTL use OUTL as manipulated value	100.0	0.0	100.0	SET1.1
AT	8 <b>88</b> 8	Auto-tuning execute selection 0 : NO PID control 1 : YES execute auto tuning	YES	NO	NO	SET1.2
*AL1	8888	Alarm1 set value (Please refer to Chapter 12)	9999	-1999	1.0	SET1.3
SOAK	5688	Alarm1 soak time Time format : hr.min	99.59	0.00	0.10	ALD1=10 or ALD1=19
HBAC	868E	HBA current setting value Upper : heater current display Down : current setting value unit : ampere(A)	100.0	0.0	1.0	INP2=4 & ALD1=9
*AL2	BBB	Alarm2 set value (Please refer to Chapter 12)	9999	-1999	1.0	SET1.4
HBAC	868E	HBA current setting value Upper : heater current display Down : current setting value	100.0	0.0	1.0	INP2=4 & ALD2=9
SOAK	Sore	Alarm2 soak time Time format : hr.min	99.59	0.00	0.10	ALD2=10 or
*AL3	863	Alarm3 set value (Please refer to Chapter 12)	9999	-1999	1.0	SET2.1
SOAK	5088	Alarm3 soak time Time format : hr.min	99.59	0.00	0.10	ALD3=10
RAMP	-828	The rate of change during SV ramp operation format : °C / minute	99.99	-19.99	10.00	ALD3=9 & SET2.1
RATE	FBEE	(Please refer to Chapter 11.7) Slave SV rate RATE SV = SV x (RATE/9999)	9999	0	9999	SET2.1 & SET0.2

### 10.5 LEVEL\_1 Parameter

\* Automatically display corresponding parameters according to different setting conditions

EX1: When alarm1 is used as HBA function, original AL1 will become HBAC display

EX2: When alarm2 is used as SOAK\_B function(ALDX= 19), original AL2 will become SOAK display

EX3: When alarm3 is used as RAMP function, original AL3 will become RAMP display

#### 10.6 Level 2 (PID Level) All Parameters Display



% If no key is pressed within 60 seconds, it will automatically return to LEVEL 1 (user level) and display PV/SV

### 10.7 LEVEL\_2 Parameter

Deremeter	Symbol	Content	Ra	Range		Hide/
Parameter	Symbol		MAX	MIN	Delault	Display
P1	8 <b>8</b> 32	Main output proportional band 0.0 : ON/OFF control Other values : proportional band setting value	200.0	0.0	3.0	
11	8888.	Main output integral time 0 : disable integral function Other values : integral time setting value	3600	0	240	
D1	8898	Main output derivative time 0 : disable derivative function Other values : derivative time setting value	900	0	60	
AT.VL	REPE	Auto tuning offset value execute auto tuning in (SV-ATVL) point	100.0	-100.0	0.0	
CYT1	EBER	Main output control cycle 0 : Linear signal 1 : SSR drive 2~150 : Relay	150	0	10	
HYS1	<i>8353</i>	Hysteresis for main output on/off control use(when P1 = 0.0 appear) heating formula : PV ≥ (SV + HYS1) → OUT1=OFF PV ≤ (SV - HYS1) → OUT1=ON cooling formula : PV ≥ (SV + HYS1) → OUT1=ON	100.0	-100.0	1.0	P1 = 0.0
P2	8828	PV ≤ (SV - HYS1) → OUT1=OFF Sub output proportional band 0.0 : ON/OFF control Other values : proportional band setting value	200.0	0.0	3.0	OUTY = 1
12	88 <b>2</b> 8.	Sub output integral time 0 : disable integral function Other values : integral time setting value	3600	0	240	OUTY = 1
D2	8828	Sub output derivative time 0 : disable derivative function Other values : derivative time setting value	900	0	60	OUTY = 1
CYT2	8988	Sub output control cycle 0 : Linear signal 1 : SSR drive 2~150 : Relay	150	0	10	OUTY = 1
HYS2	8952	Hysteresis for sub output on/off control use(when P2 = 0.0 appear)	100.0	-100.0	1.0	P2 = 0.0
GAP1	SRP 1	Control gap (for main output)	1000	-1000	0	OUTY = 1
GAP2	SRP2	Control gap (for sub output)	1000	-1000	0	OUTY = 1
LCK	8888	Function or level lock (Please refer to Chapter 10.3 Data Lock Function)	1111	0000	0000	

#### 10.8 Level 3 (Input Level) All Parameters Display



× If no key is pressed within 60 seconds, it will automatically return to LEVEL 1 (user level) and display PV/SV

### 10.9 LEVEL\_3 Parameter

Parameter	Symbol	Content	Rai	nge	Dofault	Hide/
	Symbol	Content	MAX	MIN	Delault	Display
INP1	3083 	Main input type selection Change this parameter USPL&LSPL will be reset (please refer to Chapter 4 Input Type Glossary)	AN4	K1	К1	
ANL1	RABA	Main input zero calibration (please refer to chapter 15.4)	9999	-1999	0	SET2.2
ANH1	RART	Main input span calibration (please refer to chapter 15.4) (hex display)	0x7FFF	0x0000	0x5FFF	SET2.2
DP	8 <b>88</b> 8	Decimal point position (only available in linear signal input AN1~AN4) 0 : 0000 1 : 000.0 2 : 0.00 3 : 0.000	0.000	0000	000.0	SET2.2

#### 10.9 LEVEL\_3 Parameter

Dererseter	- Cymah al	Content	Rai	nge	Defeuit	Hide/
Parameter	Symbol	Content	MAX	MIN	Derault	Display
LSPL	ESPE	Input scale low	9999	-1999		SET2.3
USPL	USPL	Input scale high	9999	-1999		SET2.3
ANL2	RAL2	Sub input zero calibration	9999	-1999	0	SET2.4
ANH2	RAR2	Sub input span calibration (hex display)	0x7FFF	0x0000	0x5FFF	SET2.4
ALD1	RL 8 1	Alarm1 mode selection (Please refer to Chapter 12.1 Alarm Mode)	19	0	11	SET3.1
ALT1	REE I	Alarm1 time setting 0.00 : Flicker 99.59 : Continued ON 0.01~99.58 : delay time Time format : min . sec	99.59	0.00	99.59	SET3.2
ALD2	<i>RL 82</i>	Alarm2 mode selection (Please refer to Chapter 12.1 Alarm Mode)	19	0	0	SET3.3
ALT2	REE2	Alarm2 time setting 0.00 : Flicker 99.59 : Continued ON 0.01~99.58 : delay time Time format : min . sec	99.59	0.00	99.59	SET3.4
ALD3	RE 83	Alarm3 mode selection (Please refer to Chapter 12.1 Alarm Mode)	18	0	0	SET4.1
ALT3	REE3	Alarm3 time setting 0.00 : Flicker 99.59 : Continued ON 0.01~99.58 : delay time Time format : min . sec	99.59	0.00	99.59	SET4.2
HYSA	<i>R958</i>	Hysteresis setting for alarm1~3	100.0	-100.0	1.0	SET4.3
CLO1	<i>EL81</i>	Main output zero calibration only for linear signal (Please refer to Chapter 14.5)	9999	0	0	SET4.4
CHO1	<i>8883</i>	Main output span calibration only for linear signal (Please refer to Chapter 14.5)	9999	0	3600	SET4.4
CLO2	8882	Sub output zero calibration only for linear signal	9999	0	0	SET5.1
CHO2	<i>ER82</i>	Sub output span calibration only for linear signal	9999	0	3600	SET5.1
CLO3	8883	Retransmission zero calibration	9999	0	0	SET5.2
СНОЗ	<i>E883</i>	Retransmission span calibration	9999	0	3600	SET5.2
*RHTC	EBEE	Dehumidification temperature If PV less than RHTC manipulated value = RHPO (Please refer to Chapter 11.5)	200.0	0.0	0.5	SET5.3
RUCY	<i>F8E9</i>	Motor valve operating time Time unit : second (Please refer to Chapter 11.6)	150	5	5	SET5.3
*RHPO	28 <b>2</b> 8	Dehumidification manipulated value 0 : OFF disable dehumidification function Other values : 0.1~100.0 manipulated value (Please refer to Chapter 11.5)	100.0	OFF	OFF	SET5.3
WAIT	<u>anae</u>	Program execution standby temperature 0 : when program executed reach SV do not waiting for PV temperature Other values : when PV= (target SV-WAIT), program entering next segment (Please refer to Chapter 13)	100.0	0	0	SET5.3

\* Automatically display corresponding parameters according to different setting conditions

EX1: when OUTY= 3(motor valve drive) original RHTC will become RUCY display EX2: when PROG= ON(program type) original RHPO will become WAIT display

Deveneter	Cumela al	Content	Rai	nge	Defeuilt	Hide/
Parameter	Symbol	Content	Range         Default           MAX         MIN         Default           1111         0000         0000           RTU         TAIE         RTU           N_82         O_81         O_81           V         254         0         1           1152         24         384           1100.0         -100.0         0           100.0         -100.0         0           2         0            2         0            5.00         0.01         0.10           5.00         0.01         0.10           COOL         HEAT         HEAT	Display		
SETA	SEER	Alarm special function setting (Please refer to Chapter 12.2)	1111	0000	0000	SET5.3
PSL	8 <b>85</b> 8	Protocol selection 0 : TAIE 1 : RTU (Please refer to communication manual)	RTU	TAIE	RTU	SET5.4
BITS	<i>83ES</i>	Data format 0 : O_81 (parity bit=odd, stop bit=1) 1 : O_82 (parity bit=odd, stop bit=2) 2 : E_81 (parity bit=even, stop bit=1) 3 : E_82 (parity bit=even, stop bit=2) 4 : N_81 (parity bit=none, stop bit=1) 5 : N_82 (parity bit=none, stop bit=2)	N_82	O_81	O_81	SET5.4
IDNO	8888	Controller station	254	0	1	SET5.4
BAUD	6808	Baud rate 0 : 24(2400) 1 : 48(4800) 2 : 96(9600) 3 : 192(19200) 4 : 384(38400) 5 : 576(57600) 6 : 1152(115200) bps	1152	24	384	SET5.4
SVOS	5985	SV bias	100.0	-100.0	0	SET6.1
PVOS	8985	PV bias PV = PV + PVOS	100.0	-100.0	0	SET6.2
UNIT	BBBE	Unit Change this parameter USPL&LSPL will be reset 0 : °C 1 : °F 2 : U (Linear signal)	2	0		SET6.3
PVFT	898E	PV digital filter The PV filter is used to eliminate noise against the measured input Unit : second	5.00	0.01	0.10	SET6.4
PV2	8892	Use for motor valve feedback value				SET7.1
OUD	8888	Control action selection 0 : HEAT reverse action 1 : COOL direct action	COOL	HEAT	HEAT	SET7.2
OPAD	8888	Super SV function enable 0 : OFF 1 : ON	ON	OFF	ON	SET7.3
HZ	8 <b>8</b> 88	Power frequency 0 : 50HZ 1 : 60HZ	50HZ	60HZ	60HZ	SET7.4

#### 10.9 LEVEL\_3 Parameter

#### 10.10 Level 4 (Setting Level) All Parameters Display



% If no key is pressed within 60 seconds, it will automatically return to LEVEL 1 (user level) and display PV/SV

#### 10.11 LEVEL\_4 Parameter

Parameter	Symbol	Content	Range		Range		Default	Hide/
i arameter	Symbol	Content	MAX	MIN	Delault	Display		
SET1	SEER	Parameters Hide/Display	1111	0000				
SET2	SEE2	Parameters Hide/Display	1111	0000				
SET3	SEE3	Parameters Hide/Display	1111	0000				
SET4	SEER	Parameters Hide/Display	1111	0000				
SET5	SEES	Parameters Hide/Display	1111	0000				
SET6	SEEB	Parameters Hide/Display	1111	0000				
SET7	SEER	Parameters Hide/Display	1111	0000				
SET8	SEE8	Parameters Hide/Display	1111	0000				
SET9	SEES	Parameters Hide/Display	1111	0000				

### 10.11 LEVEL\_4 Parameter

Devenueter	Symbol	Content	Rar	nge	Default	Hide/
Parameter	Symbol	Content	MAX	MIN	Delault	Display
SET0	SEEO	Function enable/disable	1111	0000		
INP2	<i>3092</i> ,	Sub input type selection 0 : none 1 : 10~50mV / 4~20mA / 1~5V / 2~10V (remote SV use) 2 : 0~50mV / 0~20mA / 0~5V / 0~10V (remote SV use) 3 : valve feedback 4 : CT input	4	0	0	
OUTY	<i>886</i> 9	Hardware drive selection 0 : single output control 1 : dual output control 2 : valve control with feedback 3 : valve control without feedback selection 4 : single phase control	4	0	0	
PROG	<u>Hini</u>	Program function enable 0 : OFF , SV source from keypad or communication 1 : ON , SV source from program	ON	OFF	OFF	

# 10.12 Parameters Hide/Display Table on Level 4



	0574 4	0	Hide	OUTL
	SEI1_1	1	Display	OUTL
	OFT4 0	0	Hide	AT
0000	SETT_2	1	Display	AT
0000	OFT4 2	0	Hide	AL1
	SEII_S	1	Display	AL1
		0	Hide	AL2
	SET1_4	1	Display	AL2
	SET2 1	0	Hide	AL3
	3L12_1	1	Display	AL3
	о <b>г</b> та а	0	Hide	ANL1 ANH1 DP
0000	SEIZ_Z	1	Display	ANL1 ANH1 DP
0000	0570.0	0	Hide	LSPL USPL
	SEI2_3	1	Display	LSPL USPL
		0	Hide	ANL2 ANH2
	SE12_4	1	Display	ANL2 ANH2

		0	Hide	ALD1
	SEI3_I	1	Display	ALD1
1	0570.0	0	Hide	ALT1
0000	SEI3_2	1	Display	ALT1
2000	0570.0	0	Hide	ALD2
	SE13_3	1	Display	ALD2
		0	Hide	ALT2
	SE13_4	1	Display	ALT2
	0574.4	0	Hide	ALD3
	SE14_1	1	Display	ALD3
	0574.0	0	Hide	ALT3
0000	SE14_2	1	Display	ALT3
2005	0574.0	0	Hide	HYSA
	SE14_3	1	Display	HYSA
		0	Hide	CLO1 CHO1
	SE14_4	1	Display	CLO1 CHO1

		0	Hide	CLO2 CHO2				
	SE15_1	1	Display	CLO2 CHO2				
1 1	0	0	Hide	CLO3 CHO3				
0000	SE15_2	1	Display	CLO3 CHO3				
0000		0	Hide	RUCY WAIT SETA				
	SET5_3	1	Display	RUCY WAIT SETA				
		0	Hide	PSI BITS IDNO BAUD				
	SET5_4	1	Display					
			Display					
		0	Hide	SVOS				
	SET6_1	1	Display	SVOS				
1 1		0	Hide	PVOS				
0000	SET6_2	1	Display	PVOS				
5666		0	Hide	UNIT				
	SET6_3	1	Display	UNIT				
		0	Hide	PVFT				
	SET6_4	1	Display	D/FT				
			Display					
		0	Hide	PV2				
	SET7_1	1	Display	PV2				
1 1		0	Hide	OUD				
	SET7_2	1	Display	OUD				
5668		0	Hide	OPAD				
	SET7_3	1	Display	OPAD				
	SET7_4	0	Hide	HZ				
		1	Display	HZ				
	0570 (	0	Program i	not repeat				
	SET8_1	0	Program	not repeat repeat				
	SET8_1	0 1 0	Program Program	not repeat repeat failure option				
	SET8_1 SET8_2	0 1 0 1	Program Program No power With power	not repeat repeat failure option er failure option				
L.E.E.E.	SET8_1 SET8_2	0 1 0 1 0	Program Program No power With power Program	not repeat repeat failure option er failure option starts from 0				
<u>EEEE</u>	SET8_1 SET8_2 SET8_3	0 1 0 1 0 1	Program I Program I No power With power Program s	not repeat repeat failure option er failure option starts from 0 starts from PV				
<u>LEEU</u>	SET8_1 SET8_2 SET8_3	0 1 0 1 0 1 0 1 0	Program I Program I No power With power Program s Program s reserve	not repeat repeat failure option er failure option starts from 0 starts from PV				
<u>LEE</u> E	SET8_1 SET8_2 SET8_3 SET8_4	0 1 0 1 0 1 0 1 0	Program Program No power With power Program Program reserve reserve	not repeat repeat failure option er failure option starts from 0 starts from PV				
<u>LEEU</u>	SET8_1 SET8_2 SET8_3 SET8_4	0 1 0 1 0 1 0 1 1	Program I Program I No power With power Program s Program s reserve reserve	not repeat repeat failure option er failure option starts from 0 starts from PV				
<u>EEE</u>	SET8_1 SET8_2 SET8_3 SET8_4	0 1 0 1 0 1 0 1 0	Program i Program i No power With power Program s Program s reserve reserve reserve	not repeat repeat failure option er failure option starts from 0 starts from PV				
5ē£Ē	SET8_1 SET8_2 SET8_3 SET8_4 SET9_1	0 1 0 1 0 1 0 1 0 1	Program i Program i No power With power Program s reserve reserve reserve	not repeat repeat failure option er failure option starts from 0 starts from PV				
ĒĒĒĒ	SET8_1 SET8_2 SET8_3 SET8_4 SET9_1 SET9_2	0 1 0 1 0 1 0 1 0 1 0 1 0	Program i Program i No power With power Program s reserve reserve reserve reserve Program	not repeat repeat failure option er failure option starts from 0 starts from PV Timer Unit = "Hour : Minute"				
<u>Sēbē</u>	SET8_1 SET8_2 SET8_3 SET8_4 SET9_1 SET9_2	0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1	Program i Program i No power With power Program s reserve reserve reserve reserve Program Program	not repeat repeat failure option er failure option starts from 0 starts from PV Timer Unit = "Hour : Minute" Timer Unit = "Minute : Second"				
SEE SEES	SET8_1 SET8_2 SET8_3 SET8_4 SET9_1 SET9_2	0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0	Program i Program i No power With power Program s reserve reserve reserve Program Program Program Disable tr	not repeat repeat failure option er failure option starts from 0 starts from PV				
SEEE	SET8_1 SET8_2 SET8_3 SET8_4 SET9_1 SET9_2 SET9_3	0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1	Program i Program i No power With power Program s reserve reserve Program i Program i Program i Program i Disable tr	not repeat repeat failure option er failure option starts from 0 starts from PV				
SEEE	SET8_1 SET8_2 SET8_3 SET8_4 SET9_1 SET9_2 SET9_3	0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 0	Program i Program i No power With power Program s reserve reserve Program i Program i Program i Disable tr Disable tr	not repeat repeat failure option er failure option starts from 0 starts from PV				
SEEE	SET8_1 SET8_2 SET8_3 SET8_4 SET9_1 SET9_2 SET9_3 SET9_4	0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 0 1 1 0 0 1	Program i Program i No power With power Program s reserve reserve Program i Program Program Disable tr Disable tr Enable tra	not repeat repeat failure option er failure option starts from 0 starts from PV				
SEEE	SET8_1 SET8_2 SET8_3 SET8_4 SET9_1 SET9_2 SET9_3 SET9_4	0 1 1 0 1 1 0 1 1 0 1 1 0 1 1 0 1 1 0 1 1 1 0 1 1 1 1 1 1 1 1 1 1 1 1 1	Program i Program i No power With power Program s reserve reserve reserve Program Program Disable tr Disable tr Enable tra	not repeat repeat failure option er failure option starts from 0 starts from PV Timer Unit = "Hour : Minute" Timer Unit = "Minute : Second" ansmission SV ansmission SV ansmission PV ansmission PV				
SEE	SET8_1 SET8_2 SET8_3 SET8_4 SET9_1 SET9_2 SET9_3 SET9_4	0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 0 1 0 0 0 1 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0	Program i Program i No power With power Program s reserve reserve Program Program Program Disable tr Disable tr Enable tra Disable tra	not repeat repeat failure option er failure option starts from 0 starts from PV Timer Unit = "Hour : Minute" Timer Unit = "Minute : Second" ansmission SV ansmission SV ansmission PV ansmission PV ansmission PV ansmission PV ansmission PV				
SEEE	SET8_1 SET8_2 SET8_3 SET8_4 SET9_1 SET9_2 SET9_3 SET9_4 SET0_1	0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 0 1 0 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0	Program i Program i No power With power Program s reserve reserve Program i Program Program Disable tr Disable tr Disable tr Enable tra Disable tr TTL Com	not repeat repeat failure option er failure option starts from 0 starts from PV Timer Unit = "Hour : Minute" Timer Unit = "Minute : Second" ansmission SV ansmission SV ansmission SV ansmission PV ansmission PV ansmission PV ansmission PV ansmission PV ansmission PV				
SEE SEES	SET8_1 SET8_2 SET8_3 SET8_4 SET9_1 SET9_2 SET9_3 SET9_4 SET0_1 SET0_2	0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0	Program i Program i No power With power Program s reserve reserve Program i Program i Program i Disable tr Disable tr Disable tr TTL Com TTL Com	not repeat repeat failure option er failure option starts from 0 starts from PV				
SEE SEES	SET8_1 SET8_2 SET8_3 SET8_4 SET9_1 SET9_2 SET9_3 SET9_4 SET0_1 SET0_2	0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 1 0 0 1 1 0 0 1 1 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1	Program i Program i No power With powy Program s reserve reserve Program i Program i Program i Disable tr Disable tr Disable tr TTL Com TTL Com Hide Display	not repeat repeat failure option er failure option starts from 0 starts from PV				
EEEE EEEE	SET8_1 SET8_2 SET8_3 SET8_4 SET9_1 SET9_2 SET9_3 SET9_4 SET0_1 SET0_2	0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 0 1 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0	Program i Program i No power With power Program s reserve reserve Program i Program i Program i Disable tr Disable tr Enable tra Disable tra TTL Com TTL Com Hide Display Disable R	not repeat repeat failure option er failure option starts from 0 starts from PV				
EEEE SEEE	SET8_1 SET8_2 SET8_3 SET8_4 SET9_1 SET9_2 SET9_3 SET9_4 SET0_1 SET0_2 SET0_2 SET0_3	0 1 1 0 1 1 0 1 1 0 1 1 1 1 1 1 1 1 1 1 1 1 1	Program i Program i Program s Program s reserve reserve Program i Program i Program i Disable tr Disable tr Disable tr Disable tr Disable tr Disable tr Disable tr Disable tr Enable tra	not repeat repeat failure option er failure option starts from 0 starts from PV Timer Unit = "Hour : Minute" Timer Unit = "Minute : Second" ansmission SV ansmission SV ansmission SV ansmission PV ansmission PV munication (Slave) munication (Master) RATE RATE emote SV function emote SV function				
EEEE EEEE	SET8_1 SET8_2 SET8_3 SET8_4 SET9_1 SET9_2 SET9_3 SET9_4 SET0_1 SET0_2 SET0_3	0 1 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0	Program i No power With power Program s reserve reserve Program i Program i Program i Program i Disable tr Disable tr Disable tr Disable tr TTL Com TTL Com Hide Display Disable R Enable R use output	not repeat repeat failure option er failure option starts from 0 starts from PV Timer Unit = "Hour : Minute" Timer Unit = "Minute : Second" ansmission SV ansmission SV ansmission SV ansmission PV ansmission PV munication (Slave) munication (Master) RATE RATE emote SV function emote SV function t relay "b" contact when motor valve closed				

#### 10.13 Fast Parameter Access

FY controller provides a fast parameter access operation, easy for users to quickly access communication group, program group, motor valve group related parameters

Enter fast parameter access operation: press down key for 3 seconds at any level

Leave fast parameter access operation: press down key for 3 seconds at fast parameter access operation



### 11. Functional Descriptions

### 11.1 PV bias

#### Description

The FY series controller offers PV bias for input calibration, PV bias functions correct the deviation of each sensor, as well as PV difference between controllers.

Function Diagram



Parameter

Doromotor	Symbol	Contont	Range		Default	Loval	Hide/
Parameter		Content	MAX	MIN	Delault	Levei	Display
PVOS	8205	PV bias PV = PV + PVOS	100.0	-100.0	0	Level 3	SET6.2

Examples

PV bias (PV.OS) adds bias to the Measured value(PV):

When two controllers measure the temperature of the same type of load, the measured values of the respective characteristics of the sensors are displayed as Controller A : 200°C Controller B : 195°C

As shown above, Controller B is compensated by PV offset (PV.OS) The PV.OS parameter value must be corrected by +5°C. The display value will be changed to 200°C, Same as Controller A, but Controller B will show 5°C at 0°C.

Level	Parameter	Set value	Description
4	SET6.2	1	Display PVOS
3	PVOS	5	PV adds +5°C

#### 11.2 Retransmission

#### Description

The retransmission function of the FY series controller can provide digital values for parameters such as SV or PV etc. Analog signals are transmitted to external devices according to the set range (EX: PLC AI module, inverter, etc.). transmission output signal selectable: 4~20mA, 0~20mA, 0~5V, 0~10V, 1~5V, 2~10V

Function Diagram



#### Parameter

Paramotor	Cumbol	Contont	Rai	nge	Default		Hide/
Farameter	Symbol	Content	MAX	MIN	Delault	Level	Display
SETO 2 CCCO 0:H		0 : Retransmission SV disable	1	0	0	Level 4	
JE19.3 JELD 1	1 : Retransmission SV enable	I	0	0	Level 4		
SETO 4 CCLO		0 : Retransmission PV disable	1	0	0		
5L19.4	DEED	1 : Retransmission PV enable	1	0	0	Level 4	
CI 03	0000	Retransmission zero calibration	9999	0	0	Level 3	SET5 2
				<u> </u>		201010	02.0.2
сноз	0000	Retransmission span calibration	9999	0	3600	Level 3	SET5.2
	21100			-			

#### Examples

Assume the input range (LSPL & USPL) = -50.0~600.0 retransmit PV

When the PV value is between -50.0 and 600.0, the retransmission signal is based on the PV value,

and the linear output analog signal is presented.

When the PV is less than -50.0, the retransmission signal remains at 4mA

When the PV value is greater than 600.0, the retransmission signal remains at 20mA

#### Parameter setting

Level	Parameter	er Set value Description		
3	SET9.4	1	Retransmission PV	
3	CLO3	3133	Retransmission signal low point calibration value (each controller calibrate value is different)	
3	CHO3	3508	Retransmission signal high point calibration value (each controller calibrate value is different)	



#### Notes

- 1. To order TRS function, please confirm the type of retransmission output signal and retransmit signal range.
- 2. The user can select the source to be transmitted according to the parameter SET9.4 or SET9.3. The factory default is to retransmit the PV.
- 3. Modify the parameter INP1/UNIT will reset the retransmission range.
- CLO3 & CHO3 are the calibration parameters of the re-transmission signal. It has been calibrated before leaving the factory. Do not change this parameter value.
- 5. The user only needs to set SET9.4 or SET9.3, the rest of the parameters will be set & calibrated at the factory.

#### 11.3 Remote SV

#### Description

Remote SV functions as an analog signal (4~20mA or 0~10V) generated by external devices (EX: PLC AO module, transmitter) to the Remote SV terminal of the controller, to change the SV with a preset range. Remote SV signal selection: 4~20mA, 0~20mA, 0~5V, 0~10V, 1~5V, 2~10V

#### Function Diagram



#### Parameter

Deremeter	Symbol	Contont	Range		Default		Hide/
Parameter Symbol		Content	MAX	MIN	Delault	Level	Display
SET0.3	5888	0 : Remote SV disable 1 : Remote SV enable	1	0	0	Level 4	
INP2	anpe	Sub input type selection 0 : none 1 : 10~50mV / 4~20mA / 1~5V / 2~10V (remote SV use) 2 : 0~50mV / 0~20mA / 0~5V / 0~10V (remote SV use) 3 : valve feedback 4 : CT input	4	0	0	Level 4	
ANL2	RAL2	Sub input zero calibration	9999	-1999	0	Level 3	SET2.4
ANH2	Sub input span calibration (hex display)		0x7FFF	0x0000	0x5FFF	Level 3	SET2.4

#### Examples

Input signal is K1 and its range is -50.0~600.0. When an external analog signal is input to the Remote

SV terminal, the signal will be based on the range presents linear display of SV parameters

When the signal input value is less than 4mA, the PV position shows nnn2, indicating that the signal of Remote SV is lower than the lower limit value

When the signal input value is greater than 20mA, the PV position shows uuu2, indicating that the signal of Remote SV is higher than the upper limit value



Parameter setting

Parame	ler selling		
Level	Parameter	Set value	Description
4	SET0.3	1	Enable Remote SV function
4	INP2	1	Remote SV signal=4~20mA
3	ANL2	744	Remote SV signal low point calibration value (each controller calibrate value is different)
3	ANH2	0x657C	Remote SV signal high point calibration value (each controller calibrate value is different)
Notes	\$		

1. To order Remote SV function, please confirm signal type and Remote SV input range first.

- 2. Modify the parameter INP1 & UNIT will reset the input range
- 3. The ANL2 and ANH2 are the calibration parameters of Remote SV. It has been calibrated before leaving the factory. Please do not change this parameter.

#### 11.4 Heater Break Alarm

be immediately output to notify the user.

#### Description

The HBA (Heater-Break-Alarm) function measures the heater current and displays the measured current value on the parameter HBAC upper area so that the heater status can be monitored at any time. When it is detected that the heater is disconnected or the heater current is abnormally reduced, an alarm message may

Function Diagram



Electric furnace

#### Parameter

Doromotor	Symbol	Contont	Rai	nge	Default	Loval	Hide/
Parameter Symbol		Content	MAX	MIN	Delault	Level	Display
*HBAC		HBA current setting value Upper : heater current display Down : current setting value	100.0	0.0	1.0	Level 1	INP2=4 &
		unit : ampere(A)					ALD 1-9

\* when ALD1=9, original AL1 become HBAC display

HBA operating conditions

1. Heater current is less than the setting of HBAC

- 2. OUT1 output exceeds 90%
- 3. The conditions of 1 & 2 above are established and continue to exceed 20 seconds

#### Examples

Heating system with SSR as control element, set HBAC=1.0(down area)

1.

The heater current display value HBAC = 0.0(upper area), when a heater disconnection occurs → The heater current is less than the set value of HBAC=1.0. At this point, the operating condition 1 is satisfied.

2. The heater no longer heats when the heater disconnection occurs, and the gap between the PV and SV will become larger and larger.

→ The manipulated value of OUT1 is also getting larger and larger, and eventually exceeds 90%. At this point, action condition 2 is satisfied.

3. The AL1 alarm will be activated when both 1 & 2 conditions are met and continue for more than 20 seconds.

- 12		<u> </u>				
	Level	Parameter	Set value	Description		
	1	HBAC	1.0	HBA Action Current Set Value (Unit: A)		
	4	INP2	4	CT current input		
	3	ALD1	9	HBA Alarm		
	2		10	Current low-point calibration value		
	3	ANL2	-12	(each controller calibrate value is different)		
	2		0×4527	Current High-point calibration value		
	3	ANHZ	0X4527	(each controller calibrate value is different)		

#### Notes

- ANL2 & ANH2 is the current signal calibration parameters. It has been calibrated before leaving the factory. Do not change this parameter value.
   The user only needs to set HBAC, the rest of the parameters will be set & calibrated at the factory.
   CT has two specifications: SC 80-T & SC 100-T. Please check heater wire diameter and specify required CT.

**CT** Specifications

Item	Specifications		
Model number	SC 80-T	SC 100-T	
Max. continuous current	80A	100A	
Accuracy	3%	5%	
Aperture	5.9mm	12.6mm	
Dieiectric Withstanding Voltage(Hi-pot)	2500Vrms / 1 minute	4000Vrms / 1 minute	
Vibration resistance	50 HZ, 98 m/s <sup>2</sup>		
Weight	Approx. 12 g	Approx. 30 g	

Dimensions (UNIT : mm)





#### 11.5 Dehumidification Function

#### Description

The FY controller provides dehumidification function to protect the heater. When the power is turned on, the heater is dehumidified with low power. When the dehumidification is completed, the normal power is output to the heater.

Function Diagram



#### Parameter

Paramotor	Symbol	Contont	Range		Dofault	Lovol	Hide/
Parameter Symbol		Content	MAX	MIN	Delault	Levei	Display
*RHTC	FHEE	Dehumidification temperature If PV less than RHTC manipulated value = RHPO (Please refer to Chapter 11.5)	200.0	0.0	0.5	Level 3	SET5.3
*RHPO	E886	Dehumidification manipulated value 0 : OFF disable dehumidification function Other values : 0.1~100.0 manipulated value (Please refer to Chapter 11.5)	100.0	OFF	OFF	Level 3	SET5.3
* This parame	eter is multi-dis	play, wnen OUTY≠3 display RHTC					-

\* This parameter is multi-display, wnen PROG=OFF display RHPO

#### Example

After the controller is turned on, when the PV does not reach 50°C, output will be 20% of the operation time. When the time exceeds 15 minutes or the PV is greater than 50°C, the controller will produce output of normal PID gain.

Parameter se	etting		
Level	Parameter	Set value	Description
4	SET5.3	1	Display parameter RHTC  < RHPO
1	SV	100.0	Target temperature
3	RHTC	50.0	Execute de-humidifying function when PV is lower than this temperature
3	RHPO	20.0	20% operation output when executing de-humidifying function

#### 11.6 Motor Valve Control







Parameter Setting							
Level	Parameter	Set value	value Description				
4		3	Valve cor	Valve control, no feedback			
4	OUTY	2	Valve control, feedback				
4	INP2	2	Valve control, feedback				
4	*RUCY	5	Motor valve operating time (set the operating time according to the connected valve) ※Set runtime whether there is feedback or no feedback				
4	CYT1	YT1 1.5 Motor valve switching		no feedback	1.5		
			nysteresis aujustment	feedback	1.5 or more		
4	SET0.4	0 or 1	0 : use output relay "b" contact when motor valve closed 1 : use output relay "a" contact when motor valve closed				

\* when OUTY=3, original RHTC become RUCY display

#### 11.7 RAMP & SOAK

#### Description

The FY general- purpose controller provides a single ramp and soak function, after booting completed, the SV starts to increase according to the set value of RAMP. when the soak condition is met the SOAK function will be executed according to the set value of SOAK, and driving the output and alarm to ON or OFF after the SOAK time is executed finish.

#### Parameter

- di di notor							
Parameter Symbol		Contant	Range		Dofault	Loval	Hide/
		Content	MAX	MIN	Delault	Level	Display
SOAK	0000	Alarm1 soak time					ALD1=10
(AL1)	2000	Time format : hr.min	99.59	0.00	0.10	Level 1	or
SOAK	9999	Alarm2 soak time					ALD2=10
		The formula have been determined	99.59	0.00	0.10	Level 1	or
(ALZ)	0000	lime format : nr.min					ALD2=19
SOAK	0000	Alarm3 soak time					
(AL3)	0000	Time format : hr.min	99.59	0.00	0.10	Level 1	ALD3=10
RAMP	0020	The rate of change during SV ramp					
(AL3)		operation	99.99	-19.99	99.99	Level 1	ALD3=9

format : °C / minute

※ when ALD1=10 or 19, original AL1 become SOAK display when ALD2=10 or 19, original AL2 become SOAK display when ALD3=10, original AL3 become SOAK display when ALD3=9, original AL3 become RAMP display

Parameter	Set value	Description
	10 ( <sup>SOAK_A</sup> )	Boot completed, the alarm1 is ON, when PV≥SV start the timer, alarm and control function are turned OFF in timed out. (In this mode, the time format is fixed to "hour.minute")
ALDX	<b>19</b> ( <sub>SOAK_B</sub> )	Boot completed, the alarm is ON, when PV≥SV start the timer, alarm is turned ON and the control function keep ON in timed out. (In this mode, the time format is fixed to "hour.minute")
		(In this mode, the time format is fixed to "hour.minute")

X : 1 / 2(SOAK function available in alarm1 or alarm2)

Example(1) Single RAMP+SOAK\_A (ALD3=9 + ALD1=10) Boot completed, the alarm1 is ON, SV rise 5.00°C per minute. when the PV reaches 100 °C, the temperature is kept for 10 minutes. after 10 minutes alarm1 and control function are turned OFF

Level	Parameter	Set value	Description
1	SV	100.0	Target temperature
4	SET2.1	1	Display AL3
4	SET4.1	1	Display ALD3
3	ALD1	10	AL1 as soak alarm
3	ALD3	9	Enable RAMP function
1	SOAK(AL1)	0.10	10 minute temperature maintain
1	RAMP(AL3)	5.00	5.00°C rise per minute



Example(2) Single RAMP+SOAK\_B (ALD3=9 + ALD1=19) Boot completed, the alarm1 is OFF, SV rise 5.00°C rise per minute. when the PV reaches 100 °C, the temperature is kept for 10 minutes. after 10 minutes alarm is turned ON and the control function keep ON

#### Parameter setting

Level	Parameter	Set value	Description
1	SV	100.0	Target temperature
4	SET2.1	1	Display AL3
4	SET4.1	1	Display ALD3
3	ALD1	19	AL1 as soak alarm
3	ALD3	9	Enable RAMP function
1	SOAK(AL1)	0.10	10 minute temperature maintain
1	RAMP(AL3)	5 00	5 00°C rise per minute



Example(3) use only SOAK\_A (ALD1=10) Boot completed, the alarm1 is ON, and the PV is directly controlled at 100 °C. when the PV reaches 100 °C, the temperature is kept for 10 minutes. after 10 minutes alarm1 and control function are turned OFF

	Journa		
Level	Parameter	Set value	Description
1	SV	100.0	Target temperature
3	ALD1	10	AL1 as soak alarm
1	SOAK(AL1)	00.10	10 minute temperature maintain



Example(4) use only SOAK\_B (ALD1=19) Boot completed, the alarm1 is OFF, and the PV is directly controlled at 100 °C. when the PV reaches 100 °C, the temperature is kept for 10 minutes. after 10 minutes alarm is turned ON and the control function keep ON

Level	Parameter	Set value	Description
1	SV	100.0	Target temperature
3	ALD1	10	AL1 as soak alarm
1	SOAK(AL1)	00.10	10 minute temperature maintain



### 12. Alarm Action

Description The FY controller can support up to three sets of alarm functions. Each set of alarms has 19 mode. Users can choose the most suitable alarm mode according to their needs for system protection or application.

Function Diagram



Parameter	Symbol	Content	Content Range MIN		Default	Level	Hide/ Display
AL1	RL I	Alarm1 set value	9999	-1999	1.0	Level 1	SET1.3
AL2	8882.	Alarm2 set value	9999	-1999	1.0	Level 1	SET1.4
AL3	8L3	Alarm3 set value	9999	-1999	1.0	Level 1	SET2.1
ALD1	REBT	Alarm1 mode selection (Please refer to Chapter 12.1 Alarm Mode)	19	0	11	Level 3	SET3.1
ALT1	REE3	Alarm1 time setting 0 : Flicker 99.59 : Continued ON 0.01~99.58 : delay time Time format : min . sec		0.00	99.59	Level 3	SET3.2
ALD2	Alarm2 mode selection (Please refer to Chapter 12.1 Alarm Mode)		19	0	11	Level 3	SET3.3
ALT2	Alarm2 time setting 0 : Flicker 99.59 : Continued ON 0.01~99.58 : delay time Time format : min . sec		99.59	0.00	99.59	Level 3	SET3.4
ALD3	Alarm3 mode selection (Please refer to Chapter 12.1 Alarm Mode)		18	0	11	Level 3	SET4.1
ALT3	ALT3 ALT3 ALT3 ALT3 ALT3 ALT3 ALT3 ALT3		99.59	0.00	99.59	Level 3	SET4.2
HYSA	8958	Hysteresis setting for alarm1~3	100.0	-100.0	1.0	Level 3	SET4.3
SETA	SEER	Alarm special function setting (Please refer to Chapter 12.2)	1111	0000	0000	Level 3	SET5.3

#### 12.1 Alarm Mode

🔺 : SV	🖄 : Alarm set value	X : 1 / 2 / 3 (There are up to 3 sets of alarms)			
ALD <b>X</b>	Alarm mode	Description			
0	No alarm function	Not drive any alarm relays and the corresponding LED lamp.			
1	Deviation high (With hold action)	$Formula \begin{array}{c} PV \geq (SV+ALX) \rightarrow Alarm \ ON \\ PV \leq (SV+ALX-HYSA) \rightarrow Alarm \ OFF \end{array}$			
2	Deviation low (With hold action)	$\begin{tabular}{ c c c c c } \hline & & & & & & & \\ \hline & & & & & & \\ \hline & & & &$			
3	Deviation high/low (With hold action)	$\begin{tabular}{ c c c c c c c c c c c c c c c c c c c$			
4	Band (With hold action)	$\begin{tabular}{ c c c c c } \hline & ON & OFF & ON & ON$			
5	Process high (With hold action)	$\begin{array}{c c} \hline & & & \\ \hline \end{array} \\ \hline & & & \\ \hline \hline & & & \\ \hline \end{array} \\ \hline & & & \\ \hline \hline \\ \hline & & & \\ \hline \end{array} \\ \hline \hline \\ \hline & & & \\ \hline \hline \end{array} \\ \hline \\ \hline \hline \\ \hline \hline \\ \hline \hline \\ \hline \end{array} \\ \hline \hline \hline \end{array} \\ \hline \hline \hline \end{array} \\ \hline \hline \hline \hline$			
6	Process low (With hold action)	$\begin{tabular}{ c c c c c } \hline & & & & & & & \\ \hline & & & & & & \\ \hline & & & &$			
7	Segment execute alarm	When SEG=ALX alarm ON •This mode only available in program type controller			
8	System error	The Alert action, when PV displays error message			
9	HBA (Heater Break Alarm)	Activated conditions : 1. Heater current is less the HBAC set value 2. OUT1 manipulated value exceed 90% 3. Conditions of 1 & 2 above are established and continue to exceed 20 seconds. ·Please refer to Chapter 11.4 ·This mode only available in ALD1 or ALD2			
	Single RAMP	Please refer to Chapter 11.7 This mode only available in ALD3			

# 12.1 Alarm Mode

🔺 : SV	🛆 : Alarm set value	<b>X</b> :1/2/3(	There are up to 3 sets of alarms)	
ALD <b>X</b>	Alarm mode		Descriptio n	
10	SOAK_A	alarm and control function are turned OFF in timed out. If the RAMP function is used, even if the RAMP SV has not reached the target SV, the timer will start counting as long as the condition PV≥target SV is met. •Please refer to Chapter 11.7		
11	Deviation high	•This mode only available in ALD1 or ALD2     •In this mode, the time format is fixed to "hour.minute"		
		Formula	$PV \ge (SV+ALX) \rightarrow Alarm ON$ $PV \le (SV+ALX-HYSA) \rightarrow Alarm OFF$	
12	2 Deviation low		ALX OFF SV ALX OFF SV	
		Formula	$PV \le (SV+ALX) \rightarrow Alarm ON$ $PV \ge (SV+ALX+HYSA) \rightarrow Alarm OFF$	
13	Deviation high/low		ON HYSX OFF HYSX ON ALX SV ALX	
15	Deviation highnow	Formula	$\begin{array}{l} PV \geq (SV\text{+}ALX) \rightarrow Alarm \; ON \\ PV \leq (SV\text{-}ALX) \rightarrow Alarm \; ON \\ PV \geq (SV\text{-}ALX\text{+}HYSA) \rightarrow Alarm \; OFF \\ PV \leq (SV\text{+}ALX\text{-}HYSA) \rightarrow Alarm \; OFF \end{array}$	
14	Pand			
14	Ballu	Formula	$\begin{array}{l} PV \leq (SV\text{+}ALX) \rightarrow Alarm \ ON \\ PV \geq (SV\text{+}ALX) \rightarrow Alarm \ ON \\ PV \geq (SV\text{+}ALX) \rightarrow Alarm \ OFF \\ PV \leq (SV\text{-}ALX) \rightarrow Alarm \ OFF \end{array}$	
15	Process high		HYSX ON OFF ALX	
		Formula	$PV \ge ALX \rightarrow Alarm ON$ $PV \le (ALXH-HYSA) \rightarrow Alarm OFF$	
16	Process low	low		
		Formula	$PV \ge (ALX+HYSA) \rightarrow Alarm OFF$	
17	Program run	SETA.4=0 SETA.4=1 •This mode of	When program execution, alarm action When program end, alarm action only available in program type controller	
18	System normal	The Alert act (no-error me	tion, when system in normal condition essage)	

#### 12.1 Alarm Mode

ALDX	Alarm mode	Description
19	SOAK_B	Boot completed, the alarm is OFF, when PV≥SV start the timer, alarm is turned ON and the control function keep ON in timed out. If the RAMP function is used, even if the RAMP SV has not reached the target SV, the timer will start counting as long as the condition PV≥target SV is met.
		<ul> <li>Please refer to Chapter 11.7</li> <li>This mode only available in ALD1 or ALD2</li> </ul>
		In this mode, the time format is fixed to "hour.minute"

#### 12.2 Alarm Special Setting



#### 12.3 Alarm Example





### 13. Programmable

#### Description

Programmable function is SV function that is variable to time, as user can set SV value to their needs according to timebased variation curve, which is called program setting

- 1.
- There are at most 18 sets of pattern setting Every set of pattern can at most have 8 segments 2.
- 3. Every segment include 4 settings such as ramp, soak, step and continue
- 4. Pattern can be randomly linked up, as each pattern of program contains 144 segment, at most.



#### 13.1 Parameter Setting

Parameter	Symbol	Content	Range		Default	Level	Hide/
Farameter	Symbol	Content	MAX	MIN	Delault	Levei	Display
PTN	8868	Program pattern selection 1~18	18	1	1	Level 1	PROG=ON
SEG	8588	Current program segment display	8	1	1	Level 1	PROG=ON
timr <i>£ 126</i>		Current segment remain time display Upper area : display current segment remain time Down area : display current segment executed time	99.59	0.00	0.00	Level 1	PROG=ON
SV_1	5888	Segment 1 SV	USPL	LSPL	0.0	Level 1	PROG=ON
TM_1	<i>6993</i>	Segment 1 execute time setting, this parameter determines the link between a segment and a segment or pattern and pattern END(-1) : program end in this segment 0.00 : program step change in this segment 0.01~99.58 : program in this segment execute time 99.59 : program continue execute this segment no end	99.59	-1	0.00	Level 1	PROG=ON
OUT1	BBE 3	Segment 1 output limit	100.0	0.0	100.0	Level 1	PROG=ON
SV_2	5222	Segment 2 SV	USPL	LSPL	0.0	Level 1	PROG=ON
TM_2	6223	Segment 2 execute time setting	99.59	-1	0.00	Level 1	PROG=ON
OUT2	8882	Segment 2 output limit	100.0	0.0	100.0	Level 1	PROG=ON
SV_3	5988	Segment 3 SV	USPL	LSPL	0.0	Level 1	PROG=ON
TM_3	<i>E223</i>	Segment 3 execute time setting	99.59	-1	0.00	Level 1	PROG=ON
OUT3	8883	Segment 3 output limit	100.0	0.0	100.0	Level 1	PROG=ON

#### 13.1 Parameter Setting

Deremeter	Sumbol	Contont	Range		Default	Loval	Hide/
Parameter	Symbol	Content	MAX	MIN	Default	Levei	Display
SV_4	<u>54 </u> 4	Segment 4 SV	USPL	LSPL	0.0	Level 1	PROG=ON
TM_4	6228	Segment 4 execute time setting	99.59	-1	0.00	Level 1	PROG=ON
OUT4	BBES	Segment 4 output limit		0.0	100.0	Level 1	PROG=ON
SV_5	<i>5925</i>	Segment 5 SV	USPL	LSPL	0.0	Level 1	PROG=ON
TM_5	<i>E2_5</i>	Segment 5 execute time setting	99.59	-1	0.00	Level 1	PROG=ON
OUT5	8865	Segment 5 output limit	100.0	0.0	100.0	Level 1	PROG=ON
SV_6	52.8	Segment 6 SV	USPL	LSPL	0.0	Level 1	PROG=ON
TM_6	E <u>2_</u> 6	Segment 6 execute time setting	99.59	-1	0.00	Level 1	PROG=ON
OUT6	8866	Segment 6 output limit	100.0	0.0	100.0	Level 1	PROG=ON
SV_7	59_9	Segment 7 SV	USPL	LSPL	0.0	Level 1	PROG=ON
TM_7	<u> E9_9</u>	Segment 7 execute time setting	99.59	-1	0.00	Level 1	PROG=ON
OUT7	00E 7	Segment 7 output limit	100.0	0.0	100.0	Level 1	PROG=ON
SV_8	52_8	Segment 8 SV	USPL	LSPL	0.0	Level 1	PROG=ON
TM_8	<i>E8</i>	Segment 8 execute time setting	99.59	-1	0.00	Level 1	PROG=ON
OUT8	8868	Segment 8 output limit	100.0	0.0	100.0	Level 1	PROG=ON
WAIT	686E	Program execution standby temperature 0 : when program execute do not wait for PV temperature Other values : when PV= (target SV- WAIT), program entering next segment	1000	0	0	Level 1	SET5.3
SET8.1	5EE8	Program execute repeat 0 : disable repeat function 1 : Program execute repeat	1	0	0	Level 4	
SET8.2	SET8.2 SEEB SET8.2 SEEB SET8.2 SEEB SET8.2 SEEB SET8.2 SEEB SET8.2 SEEB SET8.2 SEEB SEEB SET8.2 SEEB SEEB SEEB SEEB SEEB SEEB SEEB SEEB		1	0	0	Level 4	
SET8.3	5888	Program execute start address 0 : execute from zero 1 : execute from current PV,cut time	1	0	0	Level 4	
SET9.2	SEES	Program time format 0 : hour.minute 1 : minute.second	1	0	0	Level 4	

### 13.2 Key Operation Description

Functions Keys Description		Description	
Run	$\wedge$	Eexecuting program, PRO_LED lamp ON, Upper area shows 3 times "RUN" messages.	
Halt	$\vee$	Pause executing program, PRO_LED lights remains ON, at this moment upper area will display current temperature value and "HALT" message alternately.	
		Jump to the next segment, and it can skip segment continuously.	
Segment Jump	A + SET	Holding UP key and press SET key 1 time to skip 1 segment, press SET key 2 times to skip 2 segments, so on and so forth.	
Reset	V + SET	Stop executing program, PRO_LED lamp OFF, Upper area shows 3 times "REST" messages.	
PV/SV monitor	AM	Press the A / M key for 2 seconds to jump to the parameter OUTL, then press the A / M button for 2 seconds to jump to PV / SV monitor.	

#### 13.3 Program Initial Setting



1. Setting program time format

Parameter	LED display	Description	Default	Level
SET9.2	SEE 9	Program time format 0 : hour.minute 1 : minute.second	0	Level 4

This parameter determines the time format of timer during program execution

When SET9.2 =0, TM\_n=33.23, it indicates that the execution time of this segment is 33 hours and 23 minutes When

SET9.2 =1, TM\_n=33.23, it indicates that the execution time of this segment is 33 minutes and 23 seconds

2. Setting program execute start address

Parameter	LED display	Description	Default	Level		
SET8.3	SEEB	Program execute start address 0 : execute from zero 1 : execute from current PV,cut time	1	Level 4		
Mean program starts, CV initial value will execute according to CET9.2 activalue						

When program starts, SV initial value will execute according to SET8.3 set value (1) SET8.3 =0, PTN=1 PV=50.0 SV\_1=100 TM\_1=1.00(1 hour)

When program starts, SV will start to execute from 0.0, and SV shall reach SV\_1 in one hour

(2) SET8.3 =0, PTN=1 PV=50.0 SV\_1=100 TM\_1=1.00(1 hour)

When program starts, SV will start to execute from PV temperature of 50.0, while controller will deduct the time taken to go from 0.0 to 50.0, and SV shall reach SV\_1 in half hour

3. Setting program execute with repeat function

	•			
Parameter	LED display	Description	Default	Level
SET8.1	SEE8	Program execute repeat 0 : disable repeat function 1 : Program execute repeat	0	Level 4

When program completes the execution of the final segment, and "END" message is not shown, the program will be executed again.

4. Setting program execute with power failure protection function

Parameter	LED display	Description	Default	Level
SET8.2	SEE8	Program execute power fail protection 0 : disable power fail protection 1 : enable power fail protection	0	Level 4

power failure during program execution, if there is power failure protection function set,

controller will execute current segment program after booting finish

Assume power failure occurring in the segment\_4, ramp temperature from 100°C to 200°C, and power failure occurring at SV=125, the program will execute from 100°C (segment\_4), after controller booting finish

5. Setting program execute with wait function

Parameter	LED display	Description	Default	Level	
		Program execution standby temperature 0 : when program execute do not wait for PV			
WAIT	nH E	temperature	0.0	Level 3	
		Other values : when PV=(target SV-WAIT),			
		program entering next segment			
When program executes, if WAIT=0.0, and SV reaches set temperature, whether PV reaches target					

temperature or not, the controller will enter the next segment

When program executes, if WAIT value is not 0.0, and SV reaches set temperature, as PV has not reached target temperature, controller will wait for PV temperature to reach SV-WAIT

- (1) WAIT = 0.0 without wait function set Assume the set temperature of current segment is 100.0°C, and as SV reaches the set temperature of this segment, the controller will enter the next segment
- (2) WAIT = 5.0 with wait function set Assume the set temperature of current segment is 100.0°C, and as SV reaches the set temperature of this segment, PV temperature needs to reach 100.0-5.0 (SV-WAIT)=95.0 then entering the next segment

#### 13.4 Create Program

There are 18 sets PTN to choose and each PTN have 8 segments for setting

Program structure diagram





1.	Choose program	pattern number			
	Parameter	LED <u>d</u> ispl <u>a</u> y	Description	Default	Level
	PTN	HEII	Program pattern selection 1~18	1	Level 1

2.	Setting segment n target SV

-							
	Parameter	LED display	Description	Default	Level		
	SV_n	<i>5388</i>	Segment n SV (n=1~8)	0	Level 1		

#### 3. Setting segment n target TM

Parameter	LED display	Description	Default	Level
TM_n		Segment 1 execute time setting, this parameter determines the link between a segment and a segment or pattern and pattern END(-1) : program end in this segment 0.00 : program step change in this segment 0.01~99.58 : program in this segment execute time 99.59 : program continue execute this segment no end	0	Level 1

TM setting explain :

In segment_5(SEG_5) setting TM =END $\rightarrow$ '	When the program finishes segment_4(SEG_4), program end and display "END" message, can't enter next segment.
In segment_5(SEG_5) setting TM =0.00 $\rightarrow$ V	When the program finishes segment_4(SEG_4), enter next segment, SV change suddenly.
In segment_5(SEG_5) setting TM =10.00 →	When the program finishes segment_4(SEG_4), enter next segment and executing TM_5 setting value.
In segment_5(SEG_5) setting TM =99.59 →	When the program finishes ${\tt segment\_4}({\tt SEG\_4})$ , enter next segment and executing continuously.
Setting segment n target OUTn	

4.	Setting segment r	ng segment n target OUTn			
	Parameter	LED display	Description	Default	Level
	OUTn	BBER	Segment n output limit (n=1~8)	100.0	Level 1

#### 13.5 Program Execution Flow

The program can be up to 18 patterns. If you connect all the patterns, up to 144 segments.



#### 13.6 Program Setting Example

In pattern\_1 edit program ramp, soak, step and continue



r iograffi cuit						
Segment_1	Segment_2	Segment_3	Segment_4	Segment_5	Segment_6	Segment_7
PTN = 1	PTN = 1	PTN = 1	PTN = 1	PTN = 1	PTN = 1	PTN = 1
SV_1 = 200	SV_2 = 200	SV_3 = 250	SV_4 = 250	SV_5 = 80	SV_6 = 80	SV_7 = 0
TM_1 = 60.00	TM_2 = 30.00	TM_3 = 0.00	TM_4 = 30.00	TM_5 = 40.00	TM_6 = 45.00	$TM_7 = END$
OUT1 = 100.0	OUT2 = 100.0	OUT3 = 100.0	OUT4 = 100.0	OUT5 = 100.0	OUT6 = 100.0	OUT7 = 0.0

### 14. Modification of Output Module

### 14.1 Relay Control (1a)

Side view	Bottom view	Software Setting
OJE-SS-124LMH 250VAC, 8A		Parameter set as "CYT1 =10"

#### 14.2 Relay Control (1c)

Side view	Bottom view	Software Setting
JQ1P-24V-F 250VAC		Parameter set as "CYT1 =10"

#### 14.3 SSR Control

Top view	Bottom view	Software Setting
Volt module	Volt module	Parameter set as "CYT1 =1"
	•	

#### 14.4 Linear Control

※ : When modifying mA current module, output signal needs to be calibrated, and for detailed calibration procedure, please refer to Chap. 14.5 Output Calibration Procedure Diagram.

Top view	Bottom view	Software Setting
mA module	MTPBE	Parameter set as "CYT1 =0"



#### Output1 Signal (4mA~20mA) calibration flowchart

#### 14.6 Output Calibration Steps

1. Display CLO1 & CHO1 :



※: X is default value which does not need to be modified

#### 2. Adjust CLO1 low-point calibration value :



※ : CLO1 calibration value of each controller is different from the other

#### 3. Adjust CHO1 high-point calibration value



#### X: CHO1 calibration value of each controller is different from the other

### **15. Modification of Input Signal**

#### 15.1 Input modify to thermocouple

Jumper	Position	Software Setting
Plug 2 pcs of Jumper in t	he middle slot as shown	Conware octaining
		Parameter set as "INP1=K1~L"

#### Thermocouple calibration flowchart



#### 15.2 Input modify to RTD



#### **RTD** calibration flowchart



#### 15.3 Input modify to Linear (4~20mA)

Jumper	Position	Software Setting
Plug 2 pcs of Jumper in	the right slot as shown	
		Parameter set as "INP1=AN4"





#### 15.4 Steps For Linear Input Calibration

1. Display ANL1 \ ANH1 \ DP :



※ X is the default value which doest not require modification

2. input 4mA and djust ANL1 calibration values :



※ ANL1 calibration value of each controller is different from the other

#### 3. input 20mA and djust ANH1 calibration values :



#### ※ ANH1 calibration value of each controller is different from the other

### 16. Zero / Phase Control

#### 16.1 1φ Zero Cross Control (SCR module)

OUT1 : 1Φ SCR zero cross control Parameter setting : OUTY= 0, CYT1= 1 Wiring Setup :



CYCLE TIME = 200ms

#### 16.2 1¢ Zero Cross Control (TRIAC module)

OUT1 : 1Φ SCR zero cross control Parameter setting : OUTY= 0, CYT1= 1 Wiring Setup:



#### 16.3 3¢ Zero Cross Control (SCR module)





### 16.4 3¢ Zero Cross Control (TRIAC module)

OUT1 : 3Φ SCR zero cross control Parameter setting : OUTY= 0, CYT1= 1 Wiring Setup :



three phase three wire system

#### 16.5 1φ Phase Angle Control (SCR module)



# 16.6 1¢ Phase Angle Control (TRIAC module)

OUT1 : 1Φ SCR phase angle control Parameter setting : OUTY= 4, CYT1= 0 CLO1 = 80, CHO1 = 4300 Wiring Setup :



### 17. Troubleshooting

This chapter describes error displays and procedures to follow when problems occur.

Symbol	Text	description	Solution
in IE	INLE	Input1 Error	Check whether input loop is opened or wiring is incorrect.
ן טטט	UUU1	PV is above USPL	Check whether the input value or input type is correct or not.
nnn í	NNN1	PV is below LSPL	Check whether the input value or input type is correct or not.
Elloc	CJOR	Ambient temperature over range(>50°C)	Decrease ambient temperature
RUEF	AUTF	Auto-tunning failure	Manually set the PID value
RACE	ADCF	A/D convert failed	send for repair.
FR <u>P</u> F	RAMF	EEPROM failed	send for repair.
EBEE	CJCE	cold junction diode failure	send for repair.
ErSE	TRSF	transmission hardware failure	send for repair.
FBER	FBER	valve potentiometer feedback error	<ol> <li>check the potentiometer feedback wiring</li> <li>send for repair.</li> </ol>

### 18. FY/FU Communication Register Address Table

Deremeter	Register Address			
Parameter	Hex	Dec	R/W	
SV	0x00	0	R/W	
OUTI	0x01	1	R/W	
ΔΤ	0x02	2	R/W	
	07.02	2		
	0,02	2		
SUAN	0x03	3	R/W	
HBAC				
AL2				
SOAK	0x04	4	R/W	
HBAC				
AL3				
SOAK				
DAMD	0x05	5	R/W	
RATE		-		
PTN	0x06	6	R/W	
SEG	0x07	7	R	
TIMR	0x08	8	R	
SV 1	0x09	9	R/W	
1 1		10	R/W	
	0,00	10		
	UXUB	11	K/W	
SV_2	Ux0C	12	R/W	
TM_2	0x0D	13	R/W	
OUT2	0x0E	14	R/W	
SV 3	0x0F	15	R/W	
TM 3	0v10	16	R / W/	
	0,10	17		
0013	UX11	17	R/W	
SV_4	0x12	18	R/W	
TM_4	0x13	19	R/W	
OUT4	0x14	20	R/W	
SV 5	0x15	21	R/W	
0	0x16	22	D / W/	
	0x10	22		
0015	UX17	23	R/W	
SV_6	0x18	24	R/W	
TM_6	0x19	25	R/W	
OUT6	0x1A	26	R/W	
SV 7	0x1B	27	R/W	
TM 7	0x1C	28	R/W	
	0x10	20		
0017		29	R/W	
57_8	UXTE	30	R/W	
TM_8	0x1F	31	R/W	
OUT8	0x20	32	R/W	
SV 12	0x21	33	R/W	
TM 12	0x22	34	R/W	
OUT12	0v23	35	P/W/	
<u>SV 22</u>	0x23	35		
<u>SV_22</u>	0x24	30	R/W	
TM_22	0x25	37	R/W	
OUT22	0x26	38	R/W	
SV_32	0x27	39	R/W	
TM 32	0x28	40	R/W	
OUT32	()x29	41	R/W	
SV/ 12	0v2A	12	R / W/	
<u> </u>		42		
11/1_42	UXZB	43	K/W	
OUT42	0x2C	44	R/W	
SV_52	0x2D	45	R/W	
TM 52	0x2E	46	R/W	
OUT52	0x2F	47	R/W	
SV 62	0x30	48	R/W	
TM 62	0.21	/0		
	0x31	49		
00162	0x32	50	R/W	
SV_72	0x33	51	R/W	
TM_72	0x34	52	R/W	
OUT72	0x35	53	R/W	
SV 82	0x36	54	R/W	
TM 00	0.07	54	D / \\/	
01/7.02	0X37	50		
00182	0x38	56	R/W	
P1	0x39	57	R/W	
l1	0x3A	58	R/W	
D1	0x3B	59	R/W	
	0x3D	61	R / W/	
	0,00	60		
		02		
HYS1	0x3F	63	K/W	

Deverseter	Register /				
Parameter	Hex	Dec			
P2	0x40	64	R/W		
12	0x41	65	R/W		
D2	0x42	66	R/W		
CYT2	0x43	67	R/W		
HYS2	0x44	68	R/W		
GAP1	0x45	69	R/W		
GAP2	0x46	70	R/W		
LCK	0x47	71	R/W		
INP1	0x48	72	R/W		
ANL1	0x49	73	R/W		
ANH1	0x4A	/4	R/W		
DP	0x4B	75	R/W		
LSPL	0x4C	76	R/W		
USPL ANIL 2	0x4D	70	R/W		
	0x4E	70			
	0x41	80	R/W		
	0x50	81	R/W		
	0x52	82	R/W		
AI T2	0x53	83	R/W		
ALD3	0x54	84	R/W		
ALT3	0x55	85	R/W		
HYSA	0x56	86	R/W		
CLO1	0x57	87	R/W		
CHO1	0x58	88	R/W		
CLO2	0x59	89	R/W		
CHO2	0x5A	90	R/W		
CLO3	0x5B	91	R/W		
CHO3	0x5C	92	R/W		
RHTC		02			
RUCY	0X5D	93	R/W		
RHPO		04	D / W/		
WAIT	UXJL	94			
SETA	0x5F	95	R/W		
PSL	0x60	96	R		
BITS	0x61	97	R		
IDNO	0x62	98	R		
BAUD	0x63	99	R		
SVUS	0x64	100	R/W		
PVUS	0x65	101	R/W		
	0x00	102			
	0x07	103			
	0x00	104	R/W		
OPAD	0x64	105	R/W		
H7	0x6B	107	R/W		
SET1	0x6C	108	R/W		
SET2	0x6D	109	R/W		
SET3	0x6E	110	R/W		
SET4	0x6F	111	R/W		
SET5	0x70	112	R/W		
SET6	0x71	113	R/W		
SET7	0x72	114	R/W		
SET8	0x73	115	R/W		
SET9	0x74	116	R/W		
SET0	0x75	117	R/W		
INP2	0x76	118	R/W		
OUTY	0x77	119	K/W		
	0x87	135	R		
OBIT	0x88	136	ĸ		
	0289	13/	ĸ		
۳۷	UXOA	130	ĸ		

### 19. Glossary of Characters Used In This Manual

LED Display	0	8	2	3	7	5	0	1	2	3
Characters	0	1	2	3	4	5	6	7	8	9
LED Display	8	Ь	- 8	8	E	E	8	H	88	8
Characters	Α	В	С	D	E	F	G	Н	1	J
LED Display	2	- 8	9	88	88	8	9	8	8	E
Characters	K	L	М	N	0	Р	Q	R	S	Т
LED Display	H	8	8	3	8	- 8	E			
Characters	U	V	W	Y	Z	°C	°F			



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